

C4

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RunWorkItemRestoresForTrail 29
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EDWRESchedApi.cc**41**

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DeactivateTrailQueue 55
DecrementRunningWI.....61
FindTrailQueueOfWI 67
GenerateTrailQueues.....51
GetRunningWI 63
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LockScheduleMutex 42
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SetRunningWI.....62
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```
1  /*****
2  **
3  ** File Name: RSLstart.c
4  **
5  ** Copyright (c) 1998,1999 by EMC Corporation.
6  **
7  ** Purpose:
8  ** -----
9  ** The intent of the contents of this file is to implement the
10 ** functions the control execution of the restore for the
11 ** Library.
12 **
13 ** These functions are provided to allow:
14 ** - creation of submit objects,
15 ** - restoration and the scripts to be run before and after
16 ** - starting the restoration of a submit object.
17 **
18 ** The following functions comprise restoration management:
19 **
20 ** RSTSL_Start
21 **
22 **
23 ** Compile-Time Options:
24 ** This section must list any compile time definitions
25 ** which will affect this header.
26 **
27 *****/
28
29
30 /**
31 ** Feature test switches.
32 ** Standard defines required to turn on OS features go here.
33 **
34 ** The following is required for code that uses POSIX API's.
35 ** Remove for non-POSIX, non-portable code.
36 **
37 #define _POSIX_SOURCE 1
38
39
40 /**
41 ** System headers.
42 **
43 **
44 #include <sys/wait.h>
45
46
47 /**
48 ** Epoch headers.
49 **
50 #include <eb/eb_port.h>
51 #include <eb/rb_log.h>
52 #include <ebutil/eb_normalize.h>
53 #include <ebutil/ebutil.h>
54 #include <ebreport/ebv1.h>
55
56
57 /**
58 ** Local headers
59 **
60 */
```

```
62 #include <RSLinterns.h>
63 #include <RSLauxsupp.h>
64 #include <restore/EDMRSubmitApi.h>
65
66 #include <restore/REprogmsg.h>
67 #include <restore/dispatch_daemon.h>
68 #include <restore/EDMRProgressApi.h>
69
70 extern int RunExecutable(const boolean_ty ResetId,
71 const int RunId,
72 const char *starting_cwd,
73 const char *executable_name,
74 char **executable_argv,
75 char **executable_env,
76 int *run_exit_status,
77 boolean_ty *run_cancelled,
78 boolean_ty (*QuitTest)(void));
79
80 extern int RunWorkItemRestores(int, boolean_ty (*CancelRestoreTest)());
81
82 static eerrno_ty
83 ExecuteWorkItemRestore(int SubmitObjID,
84 boolean_ty (*QuitTest)(void));
85
86 static eerrno_ty
87 RunPrepareRestore(int SubmitObjID,
88 boolean_ty (*QuitTest)(void),
89 int *PrepareExit);
90
91 static eerrno_ty
92 RunCleanupRestore(int SubmitObjID,
93 boolean_ty (*QuitTest)(void),
94 int runphase_status,
95 int *CleanupExit);
96
97 /**
98 ** #defines, structures, typedefs local to this source file
99 **
100 #define STR_SURE(str) (str) ? str:""
101 #define REMOVE_NEWLINE(str) \
102 { \
103 int rem_n1_index; \
104 for(rem_n1_index = 0; str[rem_n1_index] != '\0'; rem_n1_index++) \
105 { \
106 if(str[rem_n1_index] == '\n') \
107 { \
108 str[rem_n1_index] = '\0'; \
109 } \
110 } \
111
112 /*****
113 ** Start
114 **
115 ** This function begins execution of the restoration of the objects in a
116 ** submit object. Its progress and requests for operator input are
117 ** returned via RSTSL_GetRestoreFeedback.
118 ** Parameters:
119 ** SubmitObjID (I) - ID of the submit object which describes the restore
120 ** QuitTest (I) - function to call to check for quit signal
121 **
122 *****/
123 eerrno_ty RSTSL_Start( int SubmitObjID, boolean_ty (*QuitTest)(
124 void))
125 {
```

```

127 1 int ret_pre;
128 1 int ret_exec;
129 1 int ret_post;
130 1 int ret_all_ok;
131 1 int PrepareExit = 0;
132 1 int CleanupExit = 0;
133 1 boolean_bly QuitFlag = FALSE;

135 1 char asctime[32];

137 1 memset(asctime, 0, 32);

139 1 (void)time(&rcp->rc_cmd_starttime);

141 1 (void)ctime_r(&rcp->rc_cmd_starttime, asctime, 32);

143 1 rcp->rc_cmd_last_waf_time = rcp->rc_cmd_starttime;

145 1 REMOVE_NEWLINE(asctime);

147 1 rbe_log_stats(0, "Restore Started at %s.", asctime);

149 1 rbe_log_stats(0, "Restore Started application type %s.",
150 1 (rcp->rc_backup_app == 0)
151 1 ? "Network"
152 1 : ((struct pluginiddata *) (
153 1 rcp->currentPiptr->iddata)
154 1 -> name );

155 1 rbe_log_stats(0, "Restore Started of \"
156 1 \"top level object: %s. template %s, trailset %s.\",
157 1 STR_SURE(rcp->rc_top_level_object_name),
158 1 STR_SURE(rcp->rc_template_name),
159 1 (rcp->rc_saveset_thread) ? "Alternate": "Primary");

162 1 rbe_log_stats(0, "Restore Started by user %s, Uid %d, Gid %d.",
163 1 STR_SURE(rcp->rc_human_uidname),
164 1 rcp->rc_human_uid, rcp->rc_human_gids[0]);

166 1 rbe_log_stats(0, "Restore Started with client destination %s.",
167 1 STR_SURE(rcp->rc_client_hostname));

169 1 /* if not a network restore,
170 1 check if plugin has its own start function */

171 1 if ( rcp->rc_backup_app != 0
172 1 && NULL != rcp->currentPiptr->piFuncArray[
173 1 piFuncIndexStartRestore ] )
174 2 {
175 2 setGlobalStatus( EDMRE_STATE_EXECUTE );
176 2 /* set RE's internal status */
177 2 ret_exec = rcp->currentPiptr->piFuncArray[
178 2 piFuncIndexStartRestore ]
179 2 ( rcp, SubmitObjectID, QuitTest);
180 2
181 2 if( QuitTest() ) /* check for abort before return */
182 2 {
183 2 rbe_log_stats( EP_RB_RECOVER_ABORT,
184 2 "The restore was quit by the user during
185 2 execution.");
186 2 setGlobalStatus( EDMRE_STATE_USER_QUIT );
187 2 /* set RE's internal status */

```

```

183 3 }
184 2 return EP_RB_RECOVER_ABORT;
185 2
186 2 if (E_SUCCESS != ret_exec)
187 2 setGlobalStatus( EDMRE_STATE_FAILED );
188 2 /* set RE's internal status */
189 2 else
190 2 setGlobalStatus( EDMRE_STATE_SUCCESSFUL );
191 2 /* set RE's internal status */
192 2
193 2 return( ret_exec );
194 2
195 1 ret_pre = RunPrepareRestore(SubmitObjectID,
196 1 QuitTest,
197 1 &PrepareExit);
198 1
199 1 if(EP_RB_RECOVER_ABORT == ret_pre)
200 1 {
201 1 rbe_log_stats(EP_RB_RECOVER_ABORT,
202 1 "The restore was quit by the user during
203 1 preparation.");
204 1 setGlobalStatus( EDMRE_STATE_USER_QUIT );
205 1 /* set RE's internal status */
206 1 return EP_RB_RECOVER_ABORT;
207 1 if(PrepareExit != 0)
208 1 {
209 1 rbe_log_stats(EP_RB_RECOVER_PREPAILED,
210 1 "The restore failed during preparation. Exit %d",
211 1 PrepareExit);
212 1 setGlobalStatus( EDMRE_STATE_FAILED );
213 1 /* set RE's internal status */
214 1 return (EP_RB_RECOVER_PREPAILED);
215 1 }
216 1 setGlobalStatus( EDMRE_STATE_EXECUTE );
217 1 /* set RE's internal status */
218 1 ret_exec = ExecuteWorkItemRestore(SubmitObjectID,
219 1 QuitTest);
220 1
221 1 if (E_SUCCESS == (
222 1 ret_all_ok = ret_exec) ) /* check if any WIS failed */
223 1 {
224 1 int local_stat;
225 1 EDMStats stats;
226 1 memset( &stats, 0, sizeof(EDMStats) );
227 1
228 1 if (0 != getRestoreStatus( 0, &stats, &local_stat ))
229 1 {
230 1 rbe_log_stats(
231 1 local_stat, "Internal error: Failed in getRestoreStatus.");
232 1 ret_exec = ret_all_ok = EP_RB_RECOVER_EXECUTEFAILED;
233 1
234 1 else if (stats.edm.failed)
235 1 {
236 1 /* if any workitems failed,
237 1 its a failure for cleanup purposes */
238 1 if (0 == stats.edm.successful)
239 1 ret_all_ok = EP_RB_RECOVER_ALLFAIL;
240 1 else if (stats.edm.successful > stats.edm.failed)
241 1 ret_all_ok = EP_RB_RECOVER_FEWFAIL;
242 1
243 1 }
244 1 }

```

```

240 3      else
241 3          ret_all_ok = EP_RB_RECOVER_MANYFAIL;
242 2      }
243 1      }
245 1      ret_post = RunCleanupRestore(SubmitObjectID,
246 1          QuitTest,
247 1          ret_all_ok,
248 1          &CleanupExit);
250 1      if(QuitFlag)
251 2      {
252 2          rbe_log_stats(EP_RB_RECOVER_ABORT,
253 2              "The restore was quit by the user during execution.
254 2              ");
255 2          setGlobalStatus( EDMRE_STATE_USER_QUIT );
256 1          return EP_RB_RECOVER_ABORT;
258 1      if (E_SUCCESS != ret_exec) /* return execute status if it failed
259 2          {
260 2              setGlobalStatus( EDMRE_STATE_FAILED );
261 2              return ret_exec;
262 1          }
264 1      if(EP_RB_RECOVER_ABORT == ret_post)
265 2      {
266 2          rbe_log_stats(EP_RB_RECOVER_ABORT,
267 2              "The restore was quit by the user during cleanup.");
268 2          setGlobalStatus( EDMRE_STATE_USER_QUIT );
269 2          return EP_RB_RECOVER_ABORT;
270 1      }
272 1      if( (CleanupExit != 0) || (E_SUCCESS != ret_post) )
273 2      {
274 2          rbe_log_stats(EP_RB_RECOVER_POSTFAILED,
275 2              "The restore failed during cleanup. Exit %d",
276 2              CleanupExit);
278 2          setGlobalStatus( EDMRE_STATE_FAILED );
279 2          return (EP_RB_RECOVER_POSTFAILED);
281 1      }
283 1      setGlobalStatus( EDMRE_STATE_SUCCESSFUL );
285 1      return( E_SUCCESS );
287 1      } /* RSTSL_Start */

```

```

292      static eerrno_t
293      ExecuteWorkItemRestore(int SubmitObjectID,
294      boolean_ty (*QuitTest)(void))
297 1      {
298 1          int ret_RunWItem;
299 1          sm_push();
301 1          rcp->error_message[0] = 0;
303 1          if(0 != (ret_RunWItem = RunWorkItemRestores(
304 2              SubmitObjectID, QuitTest)))
305 2          {
306 1              rbe_log_stats(0, "Internal error: Failed in RunWorkItemRestores");
308 1              sm_pop();
310 1              if (QuitTest() == TRUE)
311 1                  return EP_RB_RECOVER_ABORT;
313 1              if (ret_RunWItem != 0)
314 1                  return EP_RB_RECOVER_EXECUTEFAILED;
316 1              return E_SUCCESS;
317 1          }

```



```
320 #define EXECUTABLE_MAX 1024
321 static eerrno_ty
322 RunPrepareRestore(int SubmitObjectID,
323                  boolean_ty (*QuitTest)(void),
324                  int *PrepareExit)
325 {
326     char **prephaseargs = NULL;
327     char **prephaseenv = NULL;
328     int GetSostatus = 0;
329     char preexecutable[EXECUTABLE_MAX];
330     boolean_ty restore_cancelled = FALSE;
331
332     *PrepareExit = 0;
333
334     /*
335      * GetSOPrephase allocates prephaseargs & prephaseenv.
336      * This will need to be freed later.
337      */
338
339     if(0 != GetSOPrePhase(SubmitObjectID,
340                          preExecutable,
341                          EXECUTABLE_MAX,
342                          &prephaseargs,
343                          &prephaseenv,
344                          &GetSostatus))
345     {
346         rbe_log_stats(0, "Internal error: Failed in GetSOPrephase");
347         return (EP_RB_RECOVER_FATALERR);
348     }
349
350     if(0 != strcmp(preExecutable, ""))
351     {
352         setGlobalStatus( EDMRE_STATE_PREPHASE );
353         if(-1 == RunExecutable(FALSE,
354                                0,
355                                NULL,
356                                preExecutable,
357                                prephaseargs,
358                                prephaseenv,
359                                &prephaseenv,
360                                &prepareExit,
361                                &restore_cancelled,
362                                QuitTest))
363         {
364             rbe_log_stats(
365                 0, "Internal error: Failed in RunExecutable for prepare.");
366             return (EP_RB_RECOVER_FATALERR);
367         }
368         if(TRUE == restore_cancelled)
369             return (EP_RB_RECOVER_ABORT);
370     }
371
372     return( E_SUCCESS );
373 }
```

```
375 boolean_ty alwaysFalse() { return FALSE; }
```

```

377 static eerrno_ty
378 RunCleanupRestore(int SubmiObjctID,
379 boolean_ty (*QuitTest)(void),
380 int runphase_status,
381 int *CleanupExit)
382 {
383     char **postphaseargs = NULL;
384     char **postphaseenv = NULL;
385     int GetSOfstatus = 0;
386     char postExecutable[EXECUTABLE_MAX];
387     boolean_ty restore_cancelled = FALSE;
388     boolean_ty ignore_quit=FALSE;
389     *CleanupExit = 0;
390
391     /*
392     * GetsOPostPhase allocates postphaseargs & postphaseenv.
393     * This will need to be free'd later.
394     */
395     PurgeTailQueue();
396     if(0 != GetSOPostPhase(SubmiObjctID,
397 postExecutable,
398 EXECUTABLE_MAX,
399 &postphaseargs,
400 &postphaseenv,
401 &GetSOfstatus))
402     {
403         rbe_log_stats(0,"Internal error: Failed in GetSOPostPhase");
404         return (EP_RB_RECOVER_FATALERR);
405     }
406     #define RESTORE_BREAK "RESTORE_BREAK="
407     #define RESTORE_BREAK_ERROR "RESTORE_BREAK=E"
408     #define RESTORE_BREAK TRUE "RESTORE_BREAK=T"
409     #define RESTORE_BREAK FALSE "RESTORE_BREAK=F"
410     if(0 != strcmp(postExecutable, ""))
411     {
412         /*
413         * If a quit has been specified, we need to tweak the
414         * RESTORE_BREAK environment variable if set
415         */
416         char *abort=NULL;
417         if(QuitTest())
418         {
419             abort=RESTORE_BREAK_TRUE;
420         }
421         else if(0!=runphase_status)
422         {
423             abort=RESTORE_BREAK_ERROR;
424         }
425         else if(0!=runphase_status)
426         {
427             abort=RESTORE_BREAK_ERROR;
428         }
429     }
430     /*
431     * ignore_quit is set to 1 when we have already processed a BREAK
432     * (CANCEL from gui), and are using the environment variable
433     * RESTORE_BREAK_E to signal the post restore script to clean
434     * up form this break. When that happens, an ignore_quit value
435     * of 1 will cause actual quit signals to be ignores by the
436     * cleanup script, since we already know (via the environment
437     * variable) that we are in "cleanup mode" and no further signal
438     * intercepcion is necessary.
439     */
440     ignore_quit=FALSE;
441     if (NULL!=abort & NULL!=postphaseenv)

```

```

442     {
443         int isub=0;
444         char *cptr;
445         while(cptr=postphaseenv[isub])
446         {
447             if(strcmp(postphaseenv[isub], RESTORE_BREAK,strlen(
448                 RESTORE_BREAK))==0)
449             {
450                 postphaseenv[isub]=esl_strdup(abort);
451                 ignore_quit=TRUE;
452                 if(NULL!=postphaseenv[isub])
453                 {
454                     rbe_log_stats(
455                         EP_RB_RECOVER_MALLOC_FAILURE,"Allocate failed in RSLstart.c");
456                     return EP_RB_RECOVER_POSTFAILED;
457                 }
458                 isub++;
459             }
460         }
461         setGlobalStatus( EDWRE_STATE_POSTPHASE );
462         if(-1 == RunExecutable(FALSE,
463             0,
464             NULL,
465             postExecutable,
466             postphaseargs,
467             postphaseenv,
468             CleanupExit,
469             &restore_cancelled,
470             ignore_quit?alwaysFalse:QuitTest))
471         {
472             rbe_log_stats(
473                 0,"Internal error: Failed in RunExecutable for cleanup.");
474             return (EP_RB_RECOVER_FATALERR);
475         }
476         if(TRUE == restore_cancelled)
477             return (EP_RB_RECOVER_ABORT);
478         return (E_SUCCESS);
479     }
480 }

```

```
482 static eerrno_ty
483 RunExecutionOverrideRestore(int SubmitObjectID,
484                             boolean_ty (*QuitTest) (void))
485 {
486     return( E_SUCCESS );
487 }
488
```

```
489 #undef EXECUTABLE_MAX
```

```

1  /*****
2  **
3  ** File Name:   RSLwISvr.c
4  **
5  ** Copyright (c) 1998,1999 by EMC Corporation.
6  **
7  ** Purpose:
8  ** -----
9  ** The intent of the contents of this file is to implement the
10 ** functions the control execution of work item restores for
11 **
12 ** Service Library.
13 **
14 ** These functions are provided to allow:
15 **
16 ** The following functions comprise restoral management:
17 **
18 ** RunWorkItemRestores()
19 **
20 **
21 ** Compile-Time Options:
22 ** This section must list any compile time definitions
23 ** which will affect this header.
24 **
25 *****/
26
27 #define _POSIX_SOURCE 1
28
29 /*
30 * System headers.
31 */
32
33 #include <sys/time.h>
34 #include <sys/types.h>
35 #include <sys/wait.h>
36 #include <values.h>
37
38 /*
39 * Epoch headers.
40 */
41
42 #include <eb/eb_port.h>
43 #include <eb/rb_log.h>
44 #include <ebutil/ebutil.h>
45 #include <restore/Rdprogmsg.h>
46
47 /*
48 * Local headers
49 */
50
51 #include <RSLspecxits.h>
52 #include <RSLremfd.h>
53 #include <EDMRReschedapi.h>
54 #include <EDMRHandleMgrapi.h>
55 #include <RSLInterns.h>
56 #include <RSLdrmain.h>
57 #include <restore/EDMRSubmitapi.h>
58 #include <EDMRDrainapi.h>
59
60 #define STR_SURE(str) (str) ? str:""
61
62 /*
63 */

```

```

64 *
65 * RunWorkItemRestores
66 * {
67 * Set the number of drives being used for the life of the restore.
68 * SetQuitFlag = FALSE
69 * TrailRestoresLeft = { # of trail restores }
70 * TrailRestoresRunning = 0;
71 *
72 * while drive available.
73 * RunTrail -- Set drive concurrency for trail restore.
74 * TrailRestoresRunning++;
75 * while OKToRunWITForTrail
76 * StartWIRestore
77 *
78 * while(1)
79 * if(QuitTest)
80 * Send WITCancelIs
81 * SetQuitFlag = TRUE
82 * Select(from_pipe, timeout (5 seconds))
83 * for each WI that completes
84 * interperate return.
85 * Drain progress.
86 * Send final progress for work item.
87 * if(WITfailed)
88 * if(OKToReschedule && SetQuitFlag == FALSE)
89 * Add to TrailQueue
90 * if(TrailRestoresHasMoreWorkItems && SetQuitFlag == FALSE)
91 * while OKToRunWITForTrail
92 * StartWIRestore
93 * else -- RunNewTrailRestore
94 * EndTrailRestore(prevTrailQueue)
95 * TrailRestoresRunning--;
96 * TrailRestoresLeft--;
97 * while (drive available &&
98 * SetQuitFlag == FALSE &&
99 * TrailRestoresLeft)
100 *
101 * RunTrail -- Set drive concurrency for trail restore.
102 * TrailRestoresRunning++;
103 *
104 * while (
105 * OKToRunWITForTrail && SetQuitFlag == FALSE)
106 * StartWIRestore
107 * end while
108 * end while
109 * end else
110 * End for each WI completes
111 * if (((SetQuitFlag == TRUE) && (TrailRestoresRunning == 0)) ||
112 * TrailRestoresLeft == 0)
113 * return; exit loop.
114 * end while(1)
115 *
116 * }
117 */
118
119 /* Stubs */
120 static int
121 InterpretWorkItemRestoreResults(wi_restore_results *results);
122 static int
123 test_fd(int fd);
124 static void
125 DebugLogFds(char *error_msg,
126 fd_set *fds);
127

```

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129 static int 130 DetermineGlobalDriveUse(); 131 132 static int 133 test_fd_hup(int fd); 134 135 static int 136 FindTrailIDForWItem(int handle, 137 int *trailID, 138 int *status); 139 140 static int 141 SendRunningWorkItemsQuit(); 142 143 /* End Stubs */ 144 145 static int 146 Select(int nfds, 147 fd_set *readfds, 148 fd_set *writefds, 149 fd_set *exceptfds, 150 struct timeval *timeout); 151 152 static int 153 HandleWorkItemRestoreResults(int FromFD, 154 int *trailID, 155 wi_restore_results *results); 156 157 static int 158 RunWorkItemRestoresForTrail(const int trailID, 159 const int CountDrivesAvailable, 160 boolean_t (*CancelRestoreTest)(), 161 boolean_t *QuitFlag, 162 int *CountDrivesInuse); 163 164 /* 165 * RunWorkItemRestores() 166 * 167 * Runs a set of work item restores. 168 * 169 * Args: 170 * SubmitObject 171 * CancelRestoreTest(). 172 * 173 * Returns: int 0 for success. 174 */ 175 int 176 RunWorkItemRestores(int SubmitObject, boolean_t (*CancelRestoreTest)()) 177 { 178 boolean_t QuitFlag = FALSE; /* Has the user requested a quit.*/ 179 boolean_t SentQuit = FALSE; /* Have we initiated the quit. */ 180 181 int TrailRestoresRunning = 0; 182 int TrailRestoresLeft; /* The number of trail restores running. */ 183 int TrailRestoresTotal; /* The number of trail restores left. */ 184 185 /* The number of trail restores total. */ 186 int CountDrivesAvailable; /* The count of drives available. */ 187 int CountDrivesInuse = 0; /* The count of drives in use. */ 188 int temp_status; 189 int HighestActiveTrail = 0; 190 /* The trail queues are ordered from 1 to n. */ 191 192 if(debugmode) 193 { 194 (void)rbe_user_error(0, 195 "DEBUG: Running RunWorkItemRestores."); 196 } 197 /* GenerateTrailQueues() 198 * Buckets the work items into trail queues. 199 * The trail queues are sorted 200 * in the order which the restores should run. 201 */ 202 if(0 != GenerateTrailQueues(SubmitObject, 203 &trailRestoresTotal, 204 &temp_status)) 205 { 206 (void)rbe_user_error(0, 207 "Internal error: Cannot generate trail 208 queues, cannot continue."); 209 return -1; 210 } 211 TrailRestoresLeft = TrailRestoresTotal; 212 CountDrivesAvailable = DetermineGlobalDriveUse(&SubmitObject); 213 214 if(debugmode) 215 { 216 (void)rbe_user_error(0, 217 "DEBUG: RunWorkItemRestores for %d trails.", 218 TrailRestoresTotal); 219 } 220 /* 221 * This is the start up loop to get the initial work item 222 * restores started. 223 */ 224 QuitFlag = CancelRestoreTest(); 225 while((CountDrivesInuse < CountDrivesAvailable) && 226 (HighestActiveTrail < TrailRestoresTotal) && 227 (FALSE == QuitFlag)) 228 { 229 int submitObjID = 0; 230 int submitElemID = 0; 231 HighestActiveTrail++; 232 /* 233 * Activate the Trail Queue. 234 * This allows the trail queues to be used to 235 * determine the work item restores to run. 236 */ 237 if(0 != ActivateTrailQueue(HighestActiveTrail, 238 1, 239 &temp_status)) 240 { 241 (void)rbe_user_error(0, 242 "Internal error: Cannot activate trail 243 queues(1) for trailid %d, cannot continue.", 244 HighestActiveTrail); 245 return -1; 246 } 247 } 248 249 }	190 1 192 1 193 2 194 2 195 2 196 1 197 1 198 1 199 1 200 1 202 1 203 1 204 1 205 2 206 2 207 2 208 2 209 1 211 1 213 1 215 1 216 2 217 2 218 2 219 2 220 1 221 1 222 1 223 1 224 1 226 1 228 1 229 1 230 1 231 2 232 2 233 2 235 2 237 2 238 2 239 2 240 2 241 2 242 2 243 2 244 3 245 3 246 3 247 3 248 3 249 2	
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```

129 static int
130 DetermineGlobalDriveUse();
131
132 static int
133 test_fd_hup(int fd);
134
135 static int
136 FindTrailIDForWitem(int handle,
137                     int *TrailID,
138                     int *status);
139
140 static int
141 SendRunningWorkItemsQuit();
142
143 /* End Stubs */
144
145 static int
146 Select(int nfd,
147        fd_set *readfds,
148        fd_set *writefds,
149        fd_set *exceptfds,
150        struct timeval *timeout);

```

```

153 static int
154 HandleWorkItemRestoreResults(int FromFD,
155                               int *TrailID,
156                               w_l_restore_results *results);
157
158 static int
159 RunWorkItemRestoresForTrail(const int TrailID,
160                              const int CountDrivesAvailable,
161                              boolean_ty (*CancelRestoreTest)(),
162                              boolean_ty *QuitFlag,
163                              int *CountDrivesInUse);

```

```

164 /*
165  * RunWorkItemRestores()
166  *
167  * Runs a set of work item restores.
168  */

```

```

169 * Args:
170 *   SubmitObject
171 *   CancelRestoreTest().
172 *
173 * Returns: int 0 for success.
174 */

```

```

175 int
176 RunWorkItemRestores(int SubmitObject, boolean_ty (*CancelRestoreTest)()
177 )

```

```

178 {
179     boolean_ty QuitFlag = FALSE; /* Has the user requested a quit. */
180     boolean_ty SentQuit = FALSE; /* Have we initiated the quit. */

```

```

181     int TrailRestoresRunning = 0;
182     /* The number of trail restores running. */
183     int TrailRestoresLeft;
184     /* The number of trail restores left. */
185     int TrailRestoresTotal;
186     /* The number of trail restores total. */

```

```

187     int CountDrivesAvailable; /* The count of drives available. */
188     int CountDrivesInUse = 0; /* The count of drives in use. */

```

```

189     int temp_status;
190     int HighestActiveTrail = 0;
191     /* The trail queues are ordered from 1 to n. */

```

```

190 /* This is the highest trail running */

```

```

192 if(debugmode)
193 {
194     (void)rbe_user_error(0,
195                          "DEBUG: Running RunWorkItemRestores.");

```

```

196 }
197 /* GenerateTrailQueues()
198 * Buckets the work items into trail queues.
199 * The trail queues are sorted
200 * in the order which the restores should run.
201 */

```

```

202 if(0 != GenerateTrailQueues(SubmitObject,
203                              &TrailRestoresTotal,
204                              &temp_status))

```

```

205 {
206     (void)rbe_user_error(0,
207                          "Internal error: Cannot generate trail
208                          queues, cannot continue.");

```

```

209     return -1;

```

```

210 }
211 TrailRestoresLeft = TrailRestoresTotal;

```

```

212 CountDrivesAvailable = DetermineGlobalDriveUse(&SubmitObject);

```

```

213 if(debugmode)

```

```

215 {
216     (void)rbe_user_error(0,
217                          "DEBUG: RunWorkItemRestores for %d trails.",
218                          TrailRestoresTotal);

```

```

219 }
220 /* This is the start up loop to get the initial work item
221 * restores started.
222 */

```

```

223 while(CountDrivesInUse < CountDrivesAvailable) &&
224     (HighestActiveTrail < TrailRestoresTotal) &&
225     (FALSE == QuitFlag)

```

```

226 {
227     int submitObjID = 0;
228     int submitElementID = 0;

```

```

229     HighestActiveTrail++;

```

```

230 /* Activate the Trail Queue.
231 * This allows the trail queues to be used to
232 * determine the work item restores to run.

```

```

233 if(0 != ActivateTrailQueue(HighestActiveTrail,
234                             1,
235                             &temp_status))

```

```

236 {
237     (void)rbe_user_error(0,
238                          "Internal error: Cannot activate trail
239                          queues(1) for trailid %d, cannot continue.",
240                          HighestActiveTrail);

```

```

241     return -1;

```

```

242 }

```

```

243 }

```

```

244 }

```

```

245 }

```

```

246 }

```

```

247 }

```

```

248 }

```

```

249 }

```



```

251 2  /*
252 2  * This sets the number of drives and media access concurrency for
253 2  * i.e. The count of running work item restores for this trail.
254 2  * Today this is one.
255 2  */
256 2  if(0 != SetWorkItemRestoresForTrail(1, &temp_status))
257 3  {
258 3  (void)rbe_user_error(0,
259 3  "Internal error: Cannot set drive acquired(
260 2  1) for trailid %d, cannot continue.", HighestActiveTrail);
261 2  }
262 2  if (0 > (temp_status = RunWorkItemRestoresForTrail(
263 2  HighestActiveTrail,
264 2  CountDrivesAvailable,
265 2  CancelRestoreTest,
266 2  &QuitFlag,
267 3  &CountDrivesInUse)))
268 3  {
269 3  /* RunWorkItemRestoresForTrail does its own error logging. */
270 3  return -1;
271 2  }
272 2  if(temp_status == 0)
273 3  {
274 3  (void)rbe_log_stats(0,
275 3  "Trail %d restore had no work item to run(
276 3  1).", HighestActiveTrail);
277 3  /* more work may be need to recover from this error condition. */
278 2  }
279 2  if(temp_status > 0)
280 3  {
281 3  TrailRestoresRunning++;
282 2  }
283 1  } /* End while() initial startup loop */
284 1  while(1)
285 2  {
286 2  int HighestFd = 0;
287 2  fd_set WorkItemFromFds;
288 2  int retStatus;
289 2  struct timeval timeout = {5, 0};
290 2  if((QuitFlag) && (!SentQuit))
291 3  {
292 3  (void)rbe_log_stats(0,
293 3  "Restore was quit by user. Quitting restore,
294 3  this could take a while.");
295 3  }
296 3  SendRunningWorkItemsQuit();
297 3  SentQuit = TRUE;
298 2  }
299 2  if(0 != getFromSet(&WorkItemFromFds, &HighestFd, &retStatus))
300 3  {
301 3  (void)rbe_user_error(0,
302 3  "Internal error: Cannot get auxproc result
303 3  fds, cannot continue.");
304 3  }

```

```

306 3  }
307 2  }
308 2  #if 0
309 2  if(debugmode)
310 3  {
311 3  DebugLogFds("The file descriptors to wait on are ",
312 3  &WorkItemFromFds);
313 2  }
314 2  #endif
315 2  if(0 > (retStatus = Select(HighestFd + 1,
316 2  &WorkItemFromFds,
317 2  NULL, NULL,
318 2  &timeout)))
319 3  {
320 3  /* error */
321 3  (void)rbe_user_error(RBRECOVER_MKERR(errno),
322 3  "Internal error: Cannot get auxproc result
323 3  fds, cannot continue.");
324 2  }
325 2  return -1;
326 2  }
327 3  else if (0 == retStatus)
328 3  { /* timed out */
329 3  QuitFlag = CancelRestoreTest();
330 2  }
331 2  }
332 2  else
333 3  { /* Available fds */
334 3  int ReadyFds = retStatus;
335 3  int FoundFds = 0;
336 3  int index;
337 3  if(debugmode)
338 3  {
339 3  DebugLogFds("The file descriptors ready to read are ",
340 3  &WorkItemFromFds);
341 2  }
342 2  /*
343 2  * If there are available fds then we may want to
344 2  * schedule the next work item restore. We should
345 2  * check if the user initiated a quit.
346 2  */
347 2  QuitFlag = CancelRestoreTest();
348 2  for(index = 0;
349 2  (index < (HighestFd + 1)) && (FoundFds < ReadyFds);
350 2  index++)
351 3  {
352 3  int StartWorkItemForTrail = 0;
353 3  if(FD_ISSET(index, &WorkItemFromFds))
354 4  {
355 4  int TrailID;
356 4  int TrailAcquired;
357 4  wi_restore_results results;
358 4  FoundFds++;
359 5  memset(&results, 0, sizeof(wi_restore_results));
360 5  if(0 != HandleWorkItemRestoreResults(index,
361 5  &TrailID,
362 5  &results))
363 5  {
364 5  }
365 5  }
366 5  }
367 5  }
368 5  }
369 5  }
370 6  }

```


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RunWorkItemRestores	RunWorkItemRestores
<div> <div>Wed Jan 02 16:32:10 2008</div> <pre> 371 6 /* HandleWorkItemRestoresResults will do its own logging! */ 372 6 return -1; 373 5 } 374 5 /* 375 5 * This is where we may want to retry the work item 376 5 * Based on if it passes or fails 377 5 */ 379 5 CountDrivesInUse--; if (0 > (StartWorkItemForTrail = RunWorkItemRestoresForTrail(TrailID, CountDrivesAvailable, CancelRestoreTest, &QuitFlag, &CountDrivesInUse))) { /* RunWorkItemRestoresForTrail does its own logging. */ return -1; } else if (StartWorkItemForTrail == 0) /* 0 work items started above, * Lets check to see if this is the last work item * left for */ { int wiCount; if (0 != GetRunningWI(TrailID, &wiCount, &temp_status)) { (void)rbe_user_error(0, "Internal error: Cannot determine number of running work items for trail, cannot continue."); return -1; } if (debugmode) { (void)rbe_user_error(0, "DEBUG: RunWorkItemRestores no more work items left for trailid %d, but %d wiCount workitem still running.", TrailID, wiCount); } /* Testing for No work items left running or started * For this trail. */ if (((0 == wiCount) && (0 == StartWorkItemForTrail)) { TrailRestoresRunning--; TrailRestoresLeft--; if (0 != DeactivateTrailQueue(TrailID, &temp_status)) { (void)rbe_user_error(0, "Internal error: Cannot deactivate trail queue for trailid %d, cannot continue.", TrailID); return -1; } } } </pre> <div> <div>Wed Jan 02 16:32:10 2008</div> <div>RSLWISVR.C 7</div> </div> </div>	<div> <div>Wed Jan 02 16:32:10 2008</div> <pre> 432 7 /* This test is to determine, 433 7 * if a trail restore finished, 434 7 * there may be another not yet started trail, 435 7 * drive available the next trail restore will be 436 7 * started. 437 7 */ 438 7 if ((0 != TrailRestoresLeft) && 439 8 (HighestActiveTrail < TrailRestoresTotal) && 440 8 (CountDrivesInUse < CountDrivesAvailable)) 441 8 { 442 8 HighestActiveTrail++; 443 8 if (0 != ActivateTrailQueue(HighestActiveTrail, 444 8 1, 445 8 &temp_status)) 446 8 { 447 9 (void)rbe_user_error(0, 448 9 "Internal error: Cannot 449 9 activate trail queue(2) for trailid %d, cannot continue.", 450 9 HighestActiveTrail); 451 8 return -1; 452 8 } 453 8 if (0 != SetQDrivesAcquired(454 9 HighestActiveTrail, 1, &temp_status)) 455 9 { 456 9 (void)rbe_user_error(0, 457 9 "Internal error: Cannot set 458 9 drive acquired(2) for trailid %d, cannot continue.", 459 9 HighestActiveTrail); 460 8 return -1; 461 8 } 462 8 if (0 > (temp_status = RunWorkItemRestoresForTrail(463 8 HighestActiveTrail, 464 8 CountDrivesAvailable, 465 8 CancelRestoreTest, 466 9 &QuitFlag, 467 9 &CountDrivesInUse))) 468 9 { 469 8 /* RunWorkItemRestoresForTrail does its own logging. 470 8 */ 471 8 return -1; 472 8 } 473 8 if (temp_status == 0) 474 8 { 475 9 /* If this Trail Had no work items we 476 9 * Should attempt to run the next trails 477 9 * work items here. This would be an internal 478 9 * error if a trail queue had no work item 479 9 * restores. 480 9 */ 481 8 (void)rbe_log_status(0, 482 8 "Internal error: Trail %d 483 9 restore had no work item to run(1).", HighestActiveTrail); 484 8 return -1; 485 8 } 486 8 if (temp_status > 0) 487 8 { </pre> <div> <div>Wed Jan 02 16:32:10 2008</div> <div>RSLWISVR.C 8</div> </div> </div>

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<pre>484 9 /* IF at least on work item was started for this 485 9 * then we have started a new trail. 486 9 */ 487 9 TrailRestoresRunning++; 488 8 } 489 7 } 490 6 } 491 5 } 492 4 } /* end for() */ 493 3 494 2 } /* else Available fds */ 495 1 496 2 497 2 /* 498 2 * Terminate the loop if either 499 2 * ----- 500 2 * 1) Sent the work items the quit AND 501 2 * No Trail restores a running. 502 2 * OR 503 2 * 2) No more Trail restores are left. 504 2 */ 505 2 506 2 if(((0 == TrailRestoresRunning) && (SentQuit)) 507 2 (0 == TrailRestoresLeft)) 508 2 { 509 3 break; 510 3 } 511 2 512 1 } /* end while(1) */ 513 1 if((0 == TrailRestoresRunning) && (SentQuit)) 514 1 { 515 2 (void)rbe_log_stats(0, 516 2 "Restore was quit by user. 517 2 Work item restore quit."); 518 1 } 519 1 return 0; 520 1</pre>			<pre>522 /* Functions needed 523 SendRunningWorkItemsQuit(); 524 InterpretWorkItemRestoreResults(); 525 */ 526 527 static int 528 Select(int nfds, 529 fd_set *readfds, 530 fd_set *writefds, 531 fd_set *exceptfds, 532 struct timeval *timeout) 533 { 534 1 int retSelect; 535 1 536 1 do 537 2 { 538 2 retSelect = select(nfds, 539 2 readfds, 540 2 writefds, 541 2 exceptfds, 542 2 timeout); 543 1 544 1 } while ((-1 == retSelect) && (EINTR == errno)); 545 1 return retSelect; 546 1 547 }</pre>		
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Page 23 of 68	InitiateWorkItemRestore	Wed Jan 02 16:32:10 2008	Page 24 of 68	InitiateWorkItemRestore	Wed Jan 02 16:32:10 2008
550 eperno 551 InitiateWorkItemRestore (const int SubmitObjID, 552 const int SubmitElemID) 553 { 554 struct auxproc AuxprocVitals; 555 eerrno_t StartupAPResults = EXIT_FAILURE; 556 time_t StartTime; 557 int TempStatus; 558 char junk_executable[1024]; 559 char **junk_argv; 560 char **AP_env = NULL; 561 int SOSTatus; 562 char clientName[256] = ""; 563 int clientPort; 564 int status; 565 time_t EndTime; 566 /* Lets see if there are any environment variables to set. 567 * The restore of the output variables are ignored. 568 */ 569 if(E_SUCCESS != GetSOExecutionPhase(SubmitObjID, 570 junk_executable, 1024, 571 &junk_argv, 572 &AP_env, 573 &SOSTatus)) 574 { 575 (void)rbe_user_error(0, 576 "Internal Error: Could not get environment 577 variables."); 578 } 579 return -1; 580 } 581 582 if (E_SUCCESS == GetSERcmdConnect(SubmitObjID, 583 SubmitElemID, 584 clientName, 256, 585 &clientPort, 586 &SOSTatus)) 587 { 588 StartupAPResults = StartupAuxprocess(0 /* XXX */, 589 &AuxprocVitals, 590 AP_env, 591 clientName, 592 clientPort); 593 } 594 else 595 { 596 (void)rbe_user_error(0, 597 "Internal Error: Could not get Remote Client name 598 &" 599 "port to connect."); 600 return -1; 601 } 602 603 if(E_SUCCESS != StartupAPResults) 604 { 605 /* StartupAuxprocess does its own logging. */ 606 return -1; 607 } 608 609 /* 610 * We need to close the bulk fd. This file descriptor 611 * is not being used any more. If we do not close it 612 * here we will have a file descriptor leak because 613 * we won't be able to determine what it was when the 614 * work item completes. 615 */	612 1 */ 613 1 close(AuxprocVitals.xp_fd_bulk_to_x); 614 1 time(&StartTime); 615 1 616 1 617 1 if(0 != newHandleSet(AuxprocVitals.xp_fd_to_x, 618 AuxprocVitals.xp_fd_from_x, 619 AuxprocVitals.xp_fd_prog_from_x, 620 SubmitObjID, 621 SubmitElemID, 622 AuxprocVitals.xp_pid, 623 StartTime, 624 &TempStatus)) 625 { 626 (void)rbe_user_error(627 0, "Internal Error: Could not register handle set."); 628 return -1; 629 } 630 631 if(0 > StartWorkItemRestore(rcp, 632 &AuxprocVitals, 633 SubmitObjID, 634 SubmitElemID)) 635 { 636 /* 637 * StartWorkItemRestore does logging if initialization fails 638 */ 639 (void)rbe_user_error(640 0, "Error in StartWorkItemRestore SubmitObjID %d," 641 "SubmitElemID %d", SubmitObjID, 642 SubmitElemID); 643 } 644 645 /* 646 * the following code kills auxproc when recx or xcpio do not 647 * start 648 * we do not want an auxproc sitting around. 649 * if errors occur in deleteHandleSet or KillWorkItemRestore the 650 * messages are 651 * logged in those calls, plus, 652 * we already know there was an error and that 653 * is why we are doing this right now. 654 */ 655 time(&EndTime); 656 deleteHandleSet(657 AuxprocVitals.xp_fd_from_x, EndTime, EP_RB_RECOVER_ALLFAIL, &status); 658 KillWorkItemRestore(659 AuxprocVitals.xp_pid, AuxprocVitals.xp_fd_to_x); 660 return -1; 661 } 662 663 return 0; 664 } /* InitiateWorkItemRestore() */	612 1 613 1 614 1 615 1 616 1 617 1 618 1 619 1 620 1 621 1 622 1 623 1 624 1 625 1 626 2 627 2 628 2 629 1 630 1 631 1 632 1 633 1 634 1 635 1 636 2 637 2 638 2 639 2 640 2 641 2 642 2 643 2 644 2 645 2 646 2 647 2 648 2 649 2 650 2 651 2 652 2 653 2 654 2 655 2 656 1 657 1 658 1 659 1 660 1	612 1 613 1 614 1 615 1 616 1 617 1 618 1 619 1 620 1 621 1 622 1 623 1 624 1 625 1 626 2 627 2 628 2 629 1 630 1 631 1 632 1 633 1 634 1 635 1 636 2 637 2 638 2 639 2 640 2 641 2 642 2 643 2 644 2 645 2 646 2 647 2 648 2 649 2 650 2 651 2 652 2 653 2 654 2 655 2 656 1 657 1 658 1 659 1 660 1		

```

663  /*
664  *      interperate return.
665  *      Drain progress.
666  *      Send final progress for work item.
667  *      Delete the handle set.
668  */
669
670 static int
671 HandleWorkItemRestoreResults(int FromFD,
672                               int *TrailID,
673                               wi_restore_results *results)
674 {
675     int ret = 0;
676     int retries = 0;
677     int GetAuxprocResultsStatus;
678     int TempStatus;
679     int DrainResult;
680     int DrainedFD;
681     int wiCount;
682     int AuxProcPid;
683     int ToFD, getFromFD, ProgressFD;
684     time_t EndTime;
685     unsigned long jobstat;
686     int timeout = 3; /* Lets try 3 seconds */
687     boolean_t fromFDHangUp = FALSE;
688
689     ToFD = getFromFD = ProgressFD = -1;
690     while(! (fromFDHangUp))
691     {
692         GetAuxprocResultsStatus = GetAuxprocResults(FromFD, results);
693
694         if(-1 == GetAuxprocResultsStatus)
695         {
696             /* GetAuxprocResults() does its own logging */
697
698             (void)rbe_user_error(0, " Error in GetAuxprocResults");
699             return -1;
700         }
701         if(0 == GetAuxprocResultsStatus)
702         {
703             if(test_fd_hup(FromFD) == 1)
704             {
705                 fromFDHangUp = TRUE;
706             }
707         }
708
709         /* The remote result are not always going to
710          * be set. For example if the remote command
711          * is not started correctly.
712          */
713
714         if(results->local_exit_set == TRUE)
715         {
716             break;
717         }
718     }
719     else
720     {
721         sleep(1);
722         test_fd(FromFD);
723         continue;
724     }
725 }

```

```

727 1  time(&EndTime);
728 1  if(0 != PushDrainRequest(FromFD, &TempStatus))
729 1  {
730 2      (void)rbe_user_error(0,
731 2          "Internal error: Could not push drain
732 2          request, cannot continue.");
733 2      return -1;
734 2  }
735 1  /* Lets give the progress thread a chance to drain keeping busy in
736 1  * the meanwhile.
737 1  */
738 1
739 1  if(0 != FindTrailQueueOfWI(FromFD, TrailID, &TempStatus))
740 1  {
741 2      (void)rbe_user_error(0,
742 2          "Internal error: Could not find trail id for
743 2          finished work item, cannot continue.");
744 2      return -1;
745 2  }
746 1
747 1  if(0 != DecrementRunningWI(*TrailID, &wiCount, &TempStatus))
748 1  {
749 2      (void)rbe_user_error(0,
750 2          "Internal error: Could not decrement running
751 2          work items for trail, cannot continue.");
752 2      return -1;
753 2  }
754 1
755 1  if(0 != getpid(FromFD, &auxProcPid, &TempStatus))
756 1  {
757 2      (void)rbe_user_error(0,
758 2          "Internal error: Could not get auxproc pid
759 2          for work item, cannot continue.");
760 2      return -1;
761 2  }
762 1
763 1  if(0 != getHandSet(
764 1      FromFD, &ToFD, &getFromFD, &ProgressFD, &TempStatus))
765 2  {
766 2      (void)rbe_user_error(0,
767 2          "Internal error: Could not get auxproc file
768 2          descriptors for work item, cannot continue.");
769 2      return -1;
770 2  }
771 1  if(FromFD != getFromFD)
772 2  {
773 2      (void)rbe_user_error(0,
774 2          "Internal error: mismatch on from file
775 2          descriptors for work item, cannot continue.");
776 2      return -1;
777 2  }
778 1  while (0 != (ret = PopDrainResult(timeout,
779 1      &DrainResult,
780 1      &DrainedFD,
781 1      &TempStatus)) && retries < 3)
782 1  {
783 1      retries++;
784 1  }
785 2  if (ret != 0)

```

Page 27 of 68	HandleWorkItemRestoreResults	Wed Jan 02 16:32:10 2008
786 2	(void)rbe_user_error(0,	
787 2	"Internal error: Could not pop drain results,	
	cannot continue.");	
789 2	return -1;	
790 1)	
792 1	/*	
793 1	Send final Progress for work item. XXX	
794 1	*/	
796 1	/* Translate the local and remote error statuses	
797 1	* to an eperno value:	
798 1	*/	
800 1	if(0 != results->local_exit_status) /* use local error, if any */	
801 1	{	
802 2	switch (results->local_exit_status)	
803 2	{	
804 2	case XG_EXIT_ALLFAIL:	
805 2	jobstat = EP_RB_RECOVER_ALLFAIL;	
806 2	break;	
807 2	case XG_EXIT_MANYFAIL:	
808 2	jobstat = EP_RB_RECOVER_MANYFAIL;	
809 2	break;	
810 2	case XG_EXIT_FEWFAIL:	
811 2	jobstat = EP_RB_RECOVER_FEWFAIL;	
812 2	break;	
813 2	case SPEXIT_REMOTE_STDERR_PROTOCOL:	
814 2	jobstat = EP_RB_RECOVER_STDERR_FAIL;	
815 2	break;	
816 2	case XG_EXIT_STOPPED:	
817 2	default: /* check for signal termination vs all generic failures */	
818 2	if ((XG_EXIT_SIGBASE < results->local_exit_status	
819 2	XG_EXIT_STOPPED == results->local_exit_status)	
820 3	{ /* killed by signal or stopped: separate error for sigpipe */	
821 3	if (XG_EXIT_SIGBASE + SIGPIPE == results->local_exit_status)	
822 3	jobstat = EP_RB_RECOVER_SERVER_SIGPIPE;	
823 3	else	
824 3	jobstat = EP_RB_RECOVER_SERVER_SIGNAL;	
825 2	}	
826 2	else	
827 3	{ /* generic server failure, unless client failed too */	
828 3	jobstat = EP_RB_RECOVER_SERVERFAIL;	
829 3	if (0 != results->remote_exit_status)	
830 3	jobstat = EP_RB_RECOVER_BOTHFAIL;	
831 2	}	
832 1)	
833 1	else if(0 != results->remote_exit_status)	
834 1	jobstat = EP_RB_RECOVER_CLIENTFAIL;	
835 1	else	
836 1	jobstat = E_SUCCESS;	
838 1	if((0 != results->remote_exit_status)	
839 1	(0 != results->local_exit_status))	
840 2	{	
841 2	int status=0;	
842 2	int rc=0;	
843 2	char *templateName=NULL;	
844 2	char *wname=NULL;	
845 2	char *trailsetName=NULL;	
847 2	rc = getHandleSetInformation(FromFD,	
848 2	&templateName,	
849 2	&wname,	

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850 2	&trailsetName,	
851 2	&status);	
852 2	rbe_log_stats(0, "Restore Failure of \"	
853 2	"top level object: %s, template %s.",	
854 2	STR_SURE(wname),	
855 2	STR_SURE(templateName));	
856 2	free(templateName);	
857 2	free(wname);	
858 2	free(trailsetName);	
859 1	}	
861 1	if(0 != deleteHandleSet(FromFD, EndTime, jobstat, &TempStatus))	
862 2	{	
863 2	(void)rbe_user_error(0,	
864 2	"Internal error: Could not delete Handle	
866 2	Set, cannot continue.");	
867 1	}	
868 1	return -1;	
869 1	if(0 != KillWorkItemRestore(AuxProcPid,	
870 1	-1 /* Hack this arg is not needed yet	
871 2	cmd_to */))	
872 2	{	
873 2	(void)rbe_user_error(0,	
874 2	"Internal error: Could not kill finished	
875 1	auxproc, cannot continue.");	
877 1	return -1;	
878 1	}	
879 1	close(ToFD);	
880 1	close(FromFD);	
881 1	close(ProgressFD);	
882 2	if(debugmode)	
883 2	{	
884 2	(void)rbe_user_error(0,	
885 2	"DEBUG: HandleWorkItemRestoreResults Auxproc(
886 2	PID %d) just finished for trailid %d work items left = %d.",	
887 2	AuxProcPid,	
888 2	*TrailID,	
889 2	wiCount);	
890 2	}	
891 2	(void)rbe_user_error(0,	
892 2	"DEBUG: HandleWorkItemRestoreResults Auxproc(
893 2	PID %d) results are local: %d: setp:%s remote: %d set:%s.",	
894 2	AuxProcPid,	
895 2	results -> local_exit_status,	
896 2	{	
897 2	results -> local_exit_set ? "TRUE": "FALSE"	
898 1	, results -> remote_exit_status,	
899 1	{	
900 1	results -> remote_exit_set ? "TRUE": "FALSE";	
	}	
	return 0;	
	} /* End HandleWorkItemRestoreResults() */	

```

904  /*
905  ** RunWorkItemRestoresForTrail()
906  *
907  * Description
908  * This function starts all the work item for the
909  * trail. For no this is set to one but concurrency
910  * will can be supported.
911  *
912  * Args:
913  * (I) TrailID -- The id for this trail.
914  * (I) CountDrivesAvailable -- the total drives available to restore.
915  * (O) QuitFlag -- indicate whether the user has quit the restore.
916  * (O) CountDrivesInUse -- The count of trails in use by restore.
917  *
918  * Return int
919  * if -1 then an error has occurred.
920  * if 0 or greater then the number of trail restores started will be
921  * returned.
922  */
923  static int
924  RunWorkItemRestoresForTrail(const int TrailID,
925                             const int CountDrivesAvailable,
926                             boolean_t (*CancelRestoreTest)(),
927                             boolean_t *QuitFlag,
928                             int *CountDrivesInUse)
929  {
930      int DriveAcquiredForTrail;
931      int DriveConcurrencyForTrail;
932      int submitObjID;
933      int submtelementID;
934      int popResults = 0;
935      int temp_status;
936      int CountOfWorkItemRestoresStarted = 0;
937      int wiCount;
938
939      while(1)
940      {
941          (*CountDrivesInUse)++;
942
943          if((0 != (popResults = PopWIFromTrailQueue(TrailID,
944                                                    &submitObjID,
945                                                    &submtelementID,
946                                                    &temp_status))) &&
947             (SCHED_NO_MORE_JOBS != temp_status))
948          {
949              (void)rbe_user_error(0,
950                                  "Internal error: Cannot pop work item off
951                                  trail queue, cannot continue.");
952              return -1;
953          }
954          if((-1 == popResults) && (SCHED_NO_MORE_JOBS == temp_status))
955          {
956              return CountOfWorkItemRestoresStarted;
957          }
958          temp_status = InitiateWorkItemRestore(
959              submitObjID, submtelementID);
960      }
961      if(temp_status != 0)

```

```

965      {
966          /* InitiateWorkItemRestore() does its own logging */
967          (void)rbe_user_error(0, "Error in InitiateWorkItemRestore, "
968                              "submitObjID %d, submtelementID %d", submitObjID,
969                              submtelementID);
970          return -1;
971      }
972      if((0 != IncrementRunningWI(TrailID, &wiCount, &temp_status))
973         {
974             (void)rbe_user_error(0,
975                                 "Internal error: Could not increment
976                                 running work items for trail, cannot continue.");
977             return -1;
978         }
979      CountOfWorkItemRestoresStarted++;
980      if((0 != GetWQDrivesAcquired(TrailID,
981                                   &DriveAcquiredForTrail,
982                                   &temp_status))
983         {
984             (void)rbe_user_error(0,
985                                 "Internal error: Cannot get drives
986                                 acquired, cannot continue.");
987             return -1;
988         }
989      if((0 != GetWQDriveConcurrency(TrailID,
990                                     &DriveConcurrencyForTrail,
991                                     &temp_status))
992         {
993             (void)rbe_user_error(0,
994                                 "Internal error: Cannot get drive
995                                 concurrency, cannot continue.");
996             return -1;
997         }
998      *QuitFlag = CancelRestoreTest();
999      if((DriveAcquiredForTrail < DriveConcurrencyForTrail) &&
1000         ((*CountDrivesInUse) < CountDrivesAvailable) &&
1001         (FALSE == *QuitFlag))
1002      {
1003          continue;
1004      }
1005      else
1006      {
1007          break;
1008      }
1009      return CountOfWorkItemRestoresStarted;
1010      /* RunWorkItemRestoresForTrail() */
1011  }
1012  }
1013  }
1014  }

```

```
1018  /* Stub */
1019  static int DetermineGlobalDriveUse()
1020  {
1021  /* Limiting to MAXINT == not limiting... Need resource management
1022  * to do this properly.
1023  NOTE: This should now work like eb_dc_restore does.
1024  */
1025  return MAXINT;
}
```

```
1028  static int
1029  SendRunningWorkItemsQuit()
1030  {
1031  int *APlist;
1032  int count;
1033  int status;
1034  int index;
1036  if(0 != getpidlist(&count, &APlist, &status))
1037  {
1038  (void)rbe_user_error(0,
1039  "Internal error: Cannot get auxproc pid list,
1040  cannot continue.");
1041  return -1;
1042  }
1043  for(index = 0; index < count; index++)
1044  {
1045  QuitWorkItemRestore(APlist[index]);
1046  }
1047  return 0;
1048 }
```

```
1050  /*
1051  * Stub this out for now.
1052  */
1053  static int
1054  InterpretWorkItemRestoreResults(wl_restore_results *results)
1055  {
1056      return 0;
1057  }
```

```
1059  static void
1060  DebugLogFds(char *error_msg,
1061             fd_set *fds)
1062  {
1063      int index, fd_count = 0;
1064      char buffer[4096];
1065      char *bufptr = (char*)buffer;
1066
1067      for(index=0;
1068          index < 1024;
1069          index++)
1070      {
1071          if( FD_ISSET(index, fds))
1072          {
1073              int size = 0;
1074              size = sprintf(bufptr, "%d ", index);
1075              bufptr += size;
1076              fd_count++;
1077          }
1078      }
1079      rbe_log_stats(0, "%s fd_count:: %d : (%s)\n",
1080                  error_msg, fd_count, buffer);
1081  }
1082  }
```



```

1085 static int
1086 test_fd(int fd)
1087 {
1088     fd_set read_fd;
1089     int ret_select;
1090     struct timeval timeout = {0, 0};
1092     FD_ZERO(&read_fd);
1094     FD_SET(fd, &read_fd);
1096     do
1097     {
1098         ret_select = select(fd + 1, &read_fd, NULL, NULL, &timeout);
1099     } while((-1 == ret_select) && (EINTR == errno));
1100     return ret_select;
1102 }
1104

```

```

1106 /*
1107  * test_fd_hup()
1108  * Description: Test the supplied file descriptor to see if
1109  * it has had the hang up condition.
1110  *
1111  * Args:
1112  * Input fd -- the file descriptor to check for the hang up condition.
1113  *
1114  * Returns:
1115  * 1 for HUP event received on fd.
1116  * 0 No HUP event received on fd.
1117  * -1 errno set.
1118  */
1119
1120 static int
1121 test_fd_hup(int fd)
1122 {
1123     struct pollfd fds;
1124     int ret_poll;
1125
1127     if(fd < 0)
1128     {
1129         errno = EINVAL;
1130         return -1;
1131     }
1133     fds.fd = fd;
1134     fds.events = POLLIN;
1135     fds.revents = 0; /* initialize */
1137     do
1138     {
1139         ret_poll = poll(&fds, 1, 0);
1141     } while((-1 == ret_poll) && (EINVAL == errno));
1143     if(-1 == ret_poll)
1144     {
1145         return -1;
1146     }
1148     if((POLLHUP & fds.revents)
1149     {
1150         return 1;
1151     }
1152     else
1153     {
1154         return 0;
1155     }
1157 } /* end test_fd_hup() */

```



```
1  /*
2  ** Copyright 1996, 1997 EMC Corporation
3  */
4
5  /* EDMRESchedApi.cc
6  *
7  *
8  *
9  * Mission Statement: file that contains an API to manage the order
10 *                      in which
11 *                      restores occur
12 *
13 * Primary Data Acted On:
14 *
15 * Compile-Time Options:
16 *
17 * Basic idea here:
18 *
19 * are run.
20 * Currently things are ordered by where they
21 * appear in the Submit list but this will need to
22 * change in the future.
23
24 #if defined(lint)
25 static char RCS_id [] = "@(#) $RCSfile: EDMRESchedApi.cc,v $ "
26 "$Revision: 1.0 $ "
27 "$Date: 1997/02/06 20:49:15 $" ;
28 #endif
29
30 #include <esl/c_portable.h>
31 #include <esl/ep_xopen.h>
32 #include <esl/inout.h>
33
34 #include <stdlib.h>
35 #include <sys/types.h>
36 #include <pthread.h>
37
38 // Rogue Wave includes
39 #include <rw/collect.h>
40 #include <rw/rwfile.h>
41 #include <rw/vstream.h>
42 #include <rw/bintree.h>
43
44 #include <restore/REprogsq.h>
45 #include <restore/dispatch_daemon.h>
46
47 #include <restore/EDMRESsubmitApi.h>
48 #include <EDMREHandleMgrApi.h>
49 #include <EDMREScheduleWI.h>
50 #include <EDMRETrailList.h>
51 #include <EDMRESchedApi.h>
52
53 static unsigned int numberOfQueues = 0;
54 static RWBinaryTree trailists;
55 static pthread_mutex_t G_schedlemtx = PTHREAD_MUTEX_INITIALIZER;
56
57 typedef struct {
58     char templatenam[TEMPNAME_SIZE];
59     boolean_ty alternate;
60     int trailnum;
61 } findarg;
62
63 /*****
64 *****/
```

```
63 **
64 ** Routine: LockScheduleMutex
65 **
66 ** Inputs: None
67 **
68 ** Outputs: None
69 **
70 ** Return Codes:
71 ** None
72 **
73 ** Purpose: Lock the mutex for the handle tree object
74 **
75 ****
76 */
77
78 static void
79 LockScheduleMutex()
80 {
81     static boolean_ty first = TRUE;
82
83     if (first == TRUE)
84     {
85         first = FALSE;
86         pthread_mutex_init(&G_schedlemtx, NULL);
87     }
88
89     pthread_mutex_lock(&G_schedlemtx);
90 }
```

```
92  /*****
93  **
94  ** Routine: UnlockScheduleMutex
95  **
96  ** Inputs: None
97  **
98  ** Outputs: None
99  **
100 ** Return Codes:
101 ** None
102 **
103 ** Purpose: Unlock the mutex for the handle tree object
104 **
105 *****/
106 */
107
108 static void
109 UnlockScheduleMutex()
110 {
111     pthread_mutex_unlock(&g_schedulemtx);
112 }
```

```
114  /*****
115  **
116  ** Routine: LookupsScheduleWI
117  **
118  ** Inputs: int ID - trail object ID associated with element
119  **          int jobID - wi job ID associated with element
120  **
121  ** Outputs: int *status - status of the function if an error occurred
122  **          EDMRESchedWI **wi - place to put the pointer to the
123  **                  element
124  **
125  ** Return Codes:
126  **          int - 0 for success or non-zero for failure
127  **
128  ** Purpose: Finds a scheduled work item based on the trail ID and the
129  **          work item ID.
130  *****/
131  */
132
133  static int
134  LookupsScheduleWI(int ID, int jobID, EDMRESchedWI **wi,
135                    int *status)
136  {
137      EDMRETRailList *trl;
138      EDMRETRailList *ret;
139
140      if (status == NULL)
141      {
142          return -1;
143      }
144
145      if (wi == NULL)
146      {
147          *status = SCHED_BAD_PARAM;
148          return -1;
149      }
150
151      trl = new EDMRETRailList();
152
153      if (trl == NULL)
154      {
155          *status = SCHED_NO_MEMORY;
156          return -1;
157      }
158
159      trl -> setTrailQID(ID);
160
161      LookScheduleMutex();
162
163      ret = (EDMRETRailList *) trlLists.find(trl);
164
165      delete trl;
166
167      if (ret == NULL)
168      {
169          *status = SCHED_TRAIL_LOOKUP_FAILED;
170          UnlockScheduleMutex();
171          return -1;
172      }
173
174      *wi = ret -> getScheduleWI(jobID);
```

```
176 1      UnlockScheduleMutex();
178 1      if (*wi == NULL)
179 2      {
180 2          *status = SCHED_JOB_LOOKUP_FAILED;
181 2          return -1;
182 1      }
184 1      return 0;
185 }
```

```
187      /*****
188      **
189      ** Routine: LookupTrailObject
190      **
191      ** Inputs:  int ID - trail object ID
192      **
193      ** Outputs: int *status - status of the function if an error occurred
194      **
195      ** Return Codes:
196      **              int - 0 for success or non-zero for failure
197      **
198      ** Purpose: Finds a trail object based on the trail ID.
199      **
200      *****/
201      *
```

```
203      static int
204      LookupTrailObject(int ID, EDMRETrailList **trl, int *status)
205      {
206 1          EDMRETrailList *tmptrl;
207 1          EDMRETrailList *ret;
209 1          if (status == NULL)
210 2          {
211 2              return -1;
212 1          }
214 1          if (trl == NULL)
215 2          {
216 2              *status = SCHED_BAD_PARAM;
217 2              return -1;
218 1          }
220 1          tmptrl = new EDMRETrailList();
222 1          if (tmptrl == NULL)
223 2          {
224 2              *status = SCHED_NO_MEMORY;
225 2              return -1;
226 1          }
228 1          tmptrl -> setTrailID(ID);
230 1          LockScheduleMutex();
232 1          ret = (EDMRETrailList *) trailists.find(tmptrl);
234 1          UnlockScheduleMutex();
236 1          delete tmptrl;
238 1          if (ret == NULL)
239 2          {
240 2              *status = SCHED_TRAIL_LOOKUP_FAILED;
241 2              return -1;
242 1          }
244 1          *trl = ret;
246 1          return 0;
247      }
```

```
249  /*****
250  **
251  ** Routine: NewTrailObject
252  **
253  ** Inputs:  NONE
254  **
255  ** Outputs: int *status - status of the function if an error occurred
256  **
257  ** Return Codes:
258  **             int - ID of the new trail object
259  **
260  ** Purpose:  Creates a new trail object and inserts it in the trail
261  **             list.
262  *****/
263  */
264
265  int
266  NewTrailObject(int *status)
267  {
268      EDMRETrailList *tl;
269      EDMRETrailList *ret;
270
271      if (status == NULL)
272      {
273          return 0;
274      }
275
276      tl = new EDMRETrailList();
277
278      if (tl == NULL)
279      {
280          *status = SCHED_BAD_PARAM;
281          return 0;
282      }
283
284      tl -> setTrailID(++numberOfQueues);
285
286      LockScheduleMutex();
287
288      ret = (EDMRETrailList *) traillists.insert(tl);
289
290      UnlockScheduleMutex();
291
292      if (ret == NULL)
293      {
294          *status = SCHED_TRAIL_INSERT_FAILED;
295          delete tl;
296          return 0;
297      }
298
299      return numberOfQueues;
300  }
```

```
302  /*****
303  **
304  ** Routine: NewSchedWI
305  **
306  ** Inputs:  int ID - trail ID associated with new element
307  **             int submitID - submit ID associated with new element
308  **             int elementID - submit element ID associated with new
309  **                 element
310  **
311  ** Outputs: int *status - status of the function if an error occurred
312  **
313  ** Return Codes:
314  **             int - ID of the new sched WI element
315  **
316  ** Purpose:  Creates a new scheduled work item element and inserts it
317  **             in the
318  *****/
319  */
320
321  int
322  NewSchedWI(int ID, int submitID, int elementID, int *status)
323  {
324      EDMRETrailList *trl;
325      EDMRETrailList *ret;
326      EDMREScheduledWI *wi;
327      int winum = 0;
328
329      if (status == NULL)
330      {
331          return 0;
332      }
333
334      trl = new EDMRETrailList();
335
336      if (trl == NULL)
337      {
338          *status = SCHED_BAD_PARAM;
339          return 0;
340      }
341
342      trl -> setTrailID(ID);
343
344      LockScheduleMutex();
345
346      ret = (EDMRETrailList *) traillists.find(trl);
347
348      delete trl;
349
350      if (ret == NULL)
351      {
352          *status = SCHED_TRAIL_LOOKUP_FAILED;
353          UnlockScheduleMutex();
354          return 0;
355      }
356
357      winum = ret -> newScheduledWI();
358
359      if (winum <= 0)
360      {
361          *status = SCHED_NEW_JOB;
362          UnlockScheduleMutex();
363      }
```

```
363 2      }
364 1      return 0;
366 1      wi = ret -> getScheduledWI(winum);
368 1      UnlockSchedleMutex();
370 1      if (wi == NULL)
371 2      {
372 2          *status = SCHED_JOB_LOOKUP_FAILED;
373 2          return 0;
374 1      }
376 1      wi -> setSubmitObjctID(submittID);
377 1      wi -> setSubmitElementID(elementID);
379 1      return winum;
380 }
```

```
382      /*****
383      **
384      ** Routine: findTrail
385      **
386      ** Inputs: Traillist * - Traillist to check against
387      **
388      ** Outputs: findarg * - structure containing SubmitElement and status
389      **
390      ** Return Codes:
391      **      None
392      **
393      ** Purpose: Sets the status to non-zero if a match is found.
394      *****/
395      *****
396      */
398      static void
399      findTrail(IN RWCollectable* c, IN void *f)
400      {
401      1      EDMRETraillist *trl = (EDMRETraillist *) c;
402      1      findarg *fa = (findarg *) f;
403      1      char trltempl[TEMPNAME_SIZE];
405      1      trl -> getTemplateName(trltempl, sizeof(trltempl));
407      1      if (strcmp(fa->templatename, trltempl) == 0 &&
408      1          fa -> alternate == trl -> isAlternateTrailset())
409      2      {
410      2          fa -> trailnum = trl -> getTrailQID();
411      1      }
412 }
```



```
414 /*****
415 **
416 ** Routine: GenerateTrailQueues
417 **
418 ** Inputs:  int ID - submit ID
419 **
420 ** Outputs: int *status - status of the function if an error occurred
421 **          int *trailcount - place to put the trail queue count
422 **
423 ** Return Codes:
424 **              int - 0 if success and non-zero otherwise
425 **
426 ** Purpose:  Generate the schedule ordered by trail.
427 **
428 ****
429 */
430
431 int
432 GenerateTrailQueues(int ID, int *trailcount, int *status)
433 {
434     EDMRESSubmitObj *so;
435     EDMRESSubmitElement *se;
436     EDMRETrailList *trl;
437     int ret;
438     int i;
439     int numElements;
440     findarg fa;
441
442     if (status == NULL)
443     {
444         return -1;
445     }
446
447     if (trailcount == NULL)
448     {
449         *status = SCHED_BAD_PARAM;
450         return -1;
451     }
452
453     ret = LookupSubmitObject(ID, &so, status);
454
455     if (ret != 0)
456     {
457         return ret;
458     }
459
460     numElements = so -> getWICount();
461
462     for (i = 1; i < numElements + 1; i++)
463     {
464         se = so -> getSubmitElement(i);
465
466         if (se == NULL)
467         {
468             *status = SCHED_SE_LOOKUP_FAILURE;
469             break;
470         }
471
472         fa.alternate = se -> IsAlternateTrailset();
473         se -> getTemplate(fa.templateName, TEMPLATE_SIZE);
474         fa.trailnum = 0;
475
476         LockScheduleMutex();
```

```
478     trailLists.apply(findTrail, &fa);
479
480     UnlockScheduleMutex();
481
482     if (fa.trailnum == 0)
483     {
484         char setempl[TEMPLATE_SIZE];
485         fa.trailnum = NewTrailObject(status);
486
487         if (fa.trailnum == 0)
488         {
489             break;
490         }
491
492         ret = LookupTrailObject(fa.trailnum, &trl, status);
493
494         if (ret != 0)
495         {
496             break;
497         }
498
499         trl -> setSubmitID(ID);
500         trl -> setAlternateTrailset(se -> IsAlternateTrailset());
501         se -> getTemplate(setempl, sizeof(setempl));
502         trl -> setTemplateName(setempl);
503
504         ret = NewschedWI(fa.trailnum, ID, i, status);
505
506         if (ret != 0)
507         {
508             break;
509         }
510
511         *trailcount = numberOfQueues;
512         return 0;
513     }
514
515     return 0;
516 }
```

```
520 /*****
521 **
522 ** Routine: PurgeTrailQueue
523 **
524 ** Inputs: None
525 **
526 ** Outputs: None
527 **
528 ** Return Codes:
529 ** None
530 **
531 ** Purpose: Purge all lists.
532 **
533 ****
534 */
535 void
536 PurgeTrailQueue()
537 {
538     LockScheduleMutex();
539     trailLists.clearAndDestroy();
540     UnlockScheduleMutex();
541     numberOfQueues = 0;
542 }
543
544
545
546
```

```
548 /*****
549 **
550 ** Routine: ActivateTrailQueue
551 **
552 ** Inputs: int ID - trail ID
553 **          int drivecount - number of drives to use
554 **
555 ** Outputs: int *status - status of the function if an error occurred
556 **
557 ** Return Codes:
558 **          int - 0 if success and non-zero otherwise
559 **
560 ** Purpose: Active the given trail for restore.
561 **
562 ****
563 */
564 int
565 ActivateTrailQueue(int ID, int drivecount, int *status)
566 {
567     EDMRETrailList *trl;
568     int ret = 0;
569     if (status == NULL)
570     {
571         return -1;
572     }
573     ret = LookupTrailObject(ID, &trl, status);
574     if (ret != 0)
575     {
576         return ret;
577     }
578     if (trl == NULL)
579     {
580         return -1;
581     }
582     trl -> setTrailActive(TRUE);
583     trl -> setMaxDrives(drivecount);
584     return 0;
585 }
586
587
588
589
590
591
592
```

```
594 /*****
595 **
596 ** Routine: DeactivateTrailQueue
597 **
598 ** Inputs:  int ID - trail ID
599 **
600 ** Outputs: int *status - status of the function if an error occurred
601 **
602 ** Return Codes:
603 **             int - 0 if success and non-zero otherwise
604 **
605 ** Purpose:  Deactivate the given trail for restore.
606 **
607 *****/
608 */
609
610 int
611 DeactivateTrailQueue(int ID, int *status)
612 {
613     EDMRETrailList *trl;
614     int ret = 0;
615
616     if (status == NULL)
617     {
618         return -1;
619     }
620
621     ret = LookupTrailObject(ID, &trl, status);
622
623     if (ret != 0)
624     {
625         return ret;
626     }
627
628     if (trl == NULL)
629     {
630         return -1;
631     }
632
633     trl -> setTrailActive(FALSE);
634
635     return 0;
636 }
```

```
638 /*****
639 **
640 ** Routine: SetQDriveConcurrency
641 **
642 ** Inputs:  int ID - trail ID
643 **             int drivecount - number of drives to use
644 **
645 ** Outputs: int *status - status of the function if an error occurred
646 **
647 ** Return Codes:
648 **             int - 0 if success and non-zero otherwise
649 **
650 ** Purpose:  Set the drive concurrency for the given trail.
651 **
652 *****/
653 */
654
655 int
656 SetQDriveConcurrency(int ID, int drivecount, int *status)
657 {
658     EDMRETrailList *trl;
659     int ret = 0;
660
661     if (status == NULL)
662     {
663         return -1;
664     }
665
666     ret = LookupTrailObject(ID, &trl, status);
667
668     if (ret != 0)
669     {
670         return ret;
671     }
672
673     if (trl == NULL)
674     {
675         return -1;
676     }
677
678     trl -> setMaxDrives(drivecount);
679
680     return 0;
681 }
```

```
683 /*****
684 **
685 ** Routine: GetQDriveConcurrency
686 **
687 ** Inputs:  int ID - trail ID
688 **
689 ** Outputs: int *status - status of the function if an error occurred
690 **          int *drivecount - place for the number of drives to use
691 **
692 ** Return Codes:
693 **              int - 0 if success and non-zero otherwise
694 **
695 ** Purpose:  Retrieve the number of drives to use for the given trail
696 **          for restore.
697 **
698 *****/
699 */
700
701 int
702 GetQDriveConcurrency(int ID, int *drivecount, int *status)
703 {
704     EDMRETrailList *trl;
705     int ret = 0;
706
707     if (status == NULL)
708     {
709         return -1;
710     }
711
712     if (drivecount == NULL)
713     {
714         *status = SCHED_BAD_PARAM;
715         return -1;
716     }
717
718     ret = LookupTrailObject(ID, &trl, status);
719
720     if (ret != 0)
721     {
722         return ret;
723     }
724
725     if (trl == NULL)
726     {
727         return -1;
728     }
729
730     *drivecount = trl -> getMaxDrives();
731     return 0;
732 }
733
```

```
735 /*****
736 **
737 ** Routine: SetQDrivesAcquired
738 **
739 ** Inputs:  int ID - trail ID
740 **          int drivecount - the number of drives in use
741 **
742 ** Outputs: int *status - status of the function if an error occurred
743 **
744 ** Return Codes:
745 **              int - 0 if success and non-zero otherwise
746 **
747 ** Purpose:  Sets the number of drives in use for the given trail
748 **          for restore.
749 **
750 *****/
751 */
752
753 int
754 SetQDrivesAcquired(int ID, int drivecount, int *status)
755 {
756     EDMRETrailList *trl;
757     int ret = 0;
758
759     if (status == NULL)
760     {
761         return -1;
762     }
763
764     ret = LookupTrailObject(ID, &trl, status);
765
766     if (ret != 0)
767     {
768         return ret;
769     }
770
771     if (trl == NULL)
772     {
773         return -1;
774     }
775
776     trl -> setDrivesInUse(drivecount);
777     return 0;
778 }
779
```

```

761  /*****
762  **
763  ** Routine: GetQDrivesAcquired
764  **
765  ** Inputs:  int ID - trail ID
766  **
767  ** Outputs: int *status - status of the function if an error occurred
768  **          int *drivecount - a place to put the number of drives in use
769  **
770  ** Return Codes:
771  **             int - 0 if success and non-zero otherwise
772  **
773  ** Purpose:  Gets the number of drives in use for the given trail
774  **
775  **
776  *****/
797  */
799  int
800  GetQDrivesAcquired(int ID, int *drivecount, int *status)
801  {
802  1   EDMRETraillist *trl;
803  1   int ret = 0;
804  1
805  1   if (status == NULL)
806  2   {
807  2       return -1;
808  1   }
809  1
810  1   if (drivecount == NULL)
811  2   {
812  2       *status = SCHED_BAD_PARAM;
813  2       return -1;
814  1   }
815  1
816  1   ret = LookupTrailObject(ID, &trl, status);
817  1
818  1   if (ret != 0)
819  2   {
820  2       return ret;
821  1   }
822  1
823  1   if (trl == NULL)
824  2   {
825  2       return -1;
826  1   }
827  1
828  1   *drivecount = trl -> getDrivesInUse();
829  1
830  1   return 0;
831  1   }

```

```

833  /*****
834  **
835  ** Routine: IncrementRunningWI
836  **
837  ** Inputs:  int ID - trail ID
838  **
839  ** Outputs: int *wiCount - number of work items running after increment.
840  **          int *status - status of the function if an error occurred
841  **
842  ** Return Codes:
843  **             int - 0 if success and non-zero otherwise
844  **
845  ** Purpose:  Increment the running work items for the given trail.
846  **
847  **
848  *****/
849  */
850  int
851  IncrementRunningWI(int ID, int *wiCount, int *status)
852  {
853  1   EDMRETraillist *trl;
854  1   int ret = 0;
855  1
856  1   if (status == NULL)
857  2   {
858  2       return -1;
859  1   }
860  1
861  1   if (wiCount == NULL)
862  2   {
863  2       *status = SCHED_BAD_PARAM;
864  2       return -1;
865  1   }
866  1
867  1   ret = LookupTrailObject(ID, &trl, status);
868  1
869  1   if (ret != 0)
870  2   {
871  2       return ret;
872  1   }
873  1
874  1   if (trl == NULL)
875  2   {
876  2       return -1;
877  1   }
878  1
879  1   *wiCount = trl -> IncrementRunningWIs();
880  1
881  1   return 0;
882  1   }

```

```
884 /*****
885 **
886 ** Routine: DecrementRunningWI
887 **
888 ** Inputs:  int ID - trail ID
889 **
890 ** Outputs: int *wiCount - number of work items running after
891 **          int *status - status of the function if an error occurred.
892 **
893 ** Return Codes:
894 **             int - 0 if success and non-zero otherwise
895 **
896 ** Purpose: Decrement the running work items for the given trail.
897 **
898 ****
899 */
900 int
901 DecrementRunningWI(int ID, int *wiCount, int *status)
902 {
903     EDMRETRailList *trl;
904     int ret = 0;
905
906     if (status == NULL)
907     {
908         return -1;
909     }
910
911     if (wiCount == NULL)
912     {
913         *status = SCHED_BAD_PARAM;
914         return -1;
915     }
916
917     ret = LookupTrailObject(ID, &trl, status);
918
919     if (ret != 0)
920     {
921         return ret;
922     }
923
924     if (trl == NULL)
925     {
926         return -1;
927     }
928
929     *wiCount = trl -> DecrementRunningWIs();
930
931     return 0;
932 }
933
```

```
934 /*****
935 **
936 ** Routine: SetRunningWI
937 **
938 ** Inputs:  int ID - trail ID
939 **          int wiCount - number of work items to set.
940 **
941 ** Outputs: int *status - status of the function if an error occurred
942 **
943 ** Return Codes:
944 **             int - 0 if success and non-zero otherwise
945 **
946 ** Purpose: Set the running work items for the given trail.
947 **
948 ****
949 */
950 int
951 SetRunningWI(int ID, int wiCount, int *status)
952 {
953     EDMRETRailList *trl;
954     int ret = 0;
955
956     if (status == NULL)
957     {
958         return -1;
959     }
960
961     ret = LookupTrailObject(ID, &trl, status);
962
963     if (ret != 0)
964     {
965         return ret;
966     }
967
968     if (trl == NULL)
969     {
970         return -1;
971     }
972
973     trl -> setRunningWIs(wiCount);
974
975     return 0;
976 }
977
```

```

978 /*****
979 **
980 ** Routine: GetRunningWI
981 **
982 ** Inputs:  int ID - trail ID
983 **
984 ** Outputs: int *wiCount - number of work items running.
985 **          int *status - status of the function if an error occurred
986 **
987 ** Return Codes:
988 **             int - 0 if success and non-zero otherwise
989 **
990 ** Purpose:  Get the running work items for the given trail.
991 **
992 *****/
993 */
994 int
995 GetRunningWI(int ID, int *wiCount, int *status)
996 {
997     EDMRETrailList *trl;
998     int ret = 0;
999
1000     if (status == NULL)
1001     {
1002         return -1;
1003     }
1004
1005     if (wiCount == NULL)
1006     {
1007         *status = SCHED_BAD_PARAM;
1008         return -1;
1009     }
1010
1011     ret = LookupTrailObject(ID, &trl, status);
1012
1013     if (ret != 0)
1014     {
1015         return ret;
1016     }
1017
1018     if (trl == NULL)
1019     {
1020         return -1;
1021     }
1022
1023     *wiCount = trl -> getRunningWIs();
1024
1025     return 0;
1026 }

```

```

1029 /*****
1030 **
1031 ** Routine: PopWIFromTrailQueue
1032 **
1033 ** Inputs:  int ID - trail ID
1034 **
1035 ** Outputs: int *status - status of the function if an error occurred
1036 **          int *submitID - a place to put the submitID
1037 **          int *elementID - a place to put the element ID
1038 **
1039 ** Return Codes:
1040 **             int - 0 if success and non-zero otherwise
1041 **
1042 ** Purpose:  Gets the submit ID and element ID of the next work item
1043 **            to run.
1044 *****/
1045 */
1046 int
1047 PopWIFromTrailQueue(
1048     int ID, int *submitID, int *elementID, int *status)
1049 {
1050     EDMRETrailList *trl;
1051     EDMREScheduledWI *sw;
1052     int ret = 0;
1053
1054     if (status == NULL)
1055     {
1056         return -1;
1057     }
1058
1059     if (submitID == NULL || elementID == NULL)
1060     {
1061         *status = SCHED_BAD_PARAM;
1062         return -1;
1063     }
1064
1065     ret = LookupTrailObject(ID, &trl, status);
1066
1067     if (ret != 0)
1068     {
1069         return ret;
1070     }
1071
1072     if (trl == NULL)
1073     {
1074         return -1;
1075     }
1076
1077     if (trl -> isTrailActive() == FALSE)
1078     {
1079         *status = SCHED_TRAIL_NOT_ACTIVE;
1080         return -1;
1081     }
1082
1083     sw = trl -> popScheduledWI();
1084
1085     if (sw == NULL)
1086     {
1087         *status = SCHED_NO_MORE_JOBS;
1088         return -1;
1089     }

```

```
1089 1      }
1091 1      *submitID = sw -> getSubmitObjectID();
1092 1      *elementID = sw -> getSubmitElementID();
1094 1      delete sw;
1096 1      return 0;
1097      }
```

```
1099      /*****
1100      **
1101      ** Routine: AddWIToTrailQueue
1102      **
1103      ** Inputs:  int ID - trail ID
1104      **          int submitID - the submitID of the work item
1105      **          int elementID - the element ID of the work item
1106      **
1107      ** Outputs: int *status - status of the function if an error occurred
1108      **
1109      ** Return Codes:
1110      **              int - 0 if success and non-zero otherwise
1111      **
1112      ** Purpose:  Add the work item described by the submit ID and element
1113      **            ID to
1114      **            the specified trail queue.
1115      **
1116      **
1117      */
1118      int
1119      AddWIToTrailQueue(int ID, int submitID, int elementID, int *status)
1120      {
1121          int ret = 0;
1123          if (status == NULL)
1124          {
1125              return -1;
1126          }
1128          ret = NewschedWI(ID, submitID, elementID, status);
1130          if (ret <= 0)
1131          {
1132              return -1;
1133          }
1135          return 0;
1136      }
```



```
1138 /*****
1139 **
1140 ** Routine: FindTrailQueueOFWI
1141 **
1142 ** Inputs:  int handle - handle to identify work item
1143 **
1144 ** Outputs: int *status - status of the function if an error occurred
1145 **          int *ID - a place to put the trail ID
1146 **
1147 ** Return Codes:
1148 **              int - 0 if success and non-zero otherwise
1149 **
1150 ** Purpose:  Gets the trail ID of the work item.
1151 **
1152 ****
1153 */
1154
1155 int
1156 FindTrailQueueOFWI(int handle, int *ID, int *status)
1157 {
1158     EDMRESsubmitElement *se;
1159     int soID,
1160     seID;
1161     int ret;
1162     findArg fa;
1163
1164     if (status == NULL)
1165     {
1166         return -1;
1167     }
1168
1169     if (ID == NULL)
1170     {
1171         *status = SCHED_BAD_PARAM;
1172         return -1;
1173     }
1174
1175     ret = getSubmitIDs(handle, &soID, &seID, status);
1176
1177     if (ret != 0)
1178         return ret;
1179
1180     ret = LookupSubmitElement(soID, seID, &se, status);
1181
1182     if (ret != 0)
1183         return ret;
1184
1185     fa.alternate = se -> IsAlternateTrailset();
1186     se -> getTemplate(fa.templateName, TEMPLATE_SIZE);
1187     fa.trailnum = 0;
1188
1189     LockScheduleMutex();
1190
1191     trailLists.apply(findTrail, &fa);
1192
1193     UnlockScheduleMutex();
1194
1195     if (fa.trailnum == 0)
1196         return -1;
1197
1198     *ID = fa.trailnum;
1199
1200     return 0;
1201 }
```

```
1201 }
```